

## PhD Proposal 2017

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<b>Title: Design of a giant humanoid robot</b>
<b>Scientific field: Robotics design</b>
<b>Key words: Parallel Robot, Accuracy</b>

### Details for the subject:

#### **Background, Context:**

Some giant machines already exist to manipulate heavy material. They are controlled by a human operator, who makes sure the object to be manipulated is correctly handled, the weight is correctly balanced, and so on. We wish here to build a prototype of giant humanoid-shaped robot, for industrial and demonstration applications.

#### **Research subject, work plan:**

The candidate will have to design a robot with the following characteristics: large size (5m high), capable of carrying the operator, humanoid-shaped and capable of carrying external weights. All characteristics (energy, aso.) will be embedded. In comparison to machines, the robot will have a control increasing its tasks autonomy. Control and experimental validation is also expected

#### **The thesis progression will be as follows:**

- **Year 1: Understanding the problems involved. 1) Bibliographic study and positioning (6 months), leading to a research report and a presentation to the research group; 2) first numerical draft of robotic solution, evaluation of the costs.**
- **Year 2: Realizing the legs. Testing and validation of the prototype. Publication.**
- **Year 3: Realizing the arms, assembling, testing and validation of the arms then the global robot. Concluding Ph.D. Publications, finish experiments, thesis writing and defence.**

#### **References:**

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